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Machine Learning

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ALMA MATER STUDIORUM Università di Bologna An important feature of a learning machine is that its teacher will often be very largely ignorant of quite what is going on inside [...] The learning process may be regarded as a search for a form of behaviour which will satisfy the teacher (or some other criterion).

Turing, A. (1950), Computing machinery and intelligence

A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P if its performance at tasks in T, as measured by P, improves with experience E.

Mitchell, T. (1997), Machine Learning

Machine learning is currently **one of the hottest topic** within Artificial Intelligence and Computer Science in general.

All the most important ICT companies all over the world are **investing money** and **hiring people** with a strong background in machine learning: Google, Facebook, IBM, Baidu, Disney, ...

Why?

Because they have tons of data...

... and they need some way to make sense of it !

An overwhelming amount of data



Figure source: http://www.domo.com/

• Classify incoming e-mails as spam or not



Figure source: http://www.resilientsystems.co.uk/

• Forecast Apple stock price in the next three hours



• Make a diagnosis based on patient examinations



The average person is likely to generate more than one million gigabytes of health-related data in their lifetime. Equivalent to 300 million books.

IBM Watson Health

• Recognize digits in zipcode forms

80322-4129 80206 40004 LYZIO J 8 78 05753 ,5502 75716 35460 A4209

Figure source: [LeCun et al., 1989]

• Teach a robot to grasp a mug



Figure source: http://www.informatik.uni-bremen.de/

• Design a drug/molecule with certain properties



Figure source: http://pande.stanford.edu/

• Translate text from one language into another



• Convert a speech into text



Automatically write the caption of an image





A herd of elephants walking across a dry grass field.



A close up of a cat laying on a couch.

Marco Lippi

Figure source: Google Research



A red motorcycle parked on the side of the road.





A vellow school bus parked in a parking lot.





A refrigerator filled with lots of food and drinks.



• Beat the world's top Go player (March 2016 !)



Figure source: Google Research

Basics

Learning paradigms:

- Supervised Learning
- Unsupervised Learning
- Reinforcement Learning

How to assess the quality of a machine learning system ?

- Performance measurements
- Overfitting and cross-validation

General categories of machine learning models

- Symbolic approaches
- Sub-symbolic (connectionist) approaches

Supervised machine learning problem:

• find a mapping between input/output variables, directly from data observations

Main framework:

- given observation $x \in \mathcal{X}$
- target of prediction $y \in \mathcal{Y}$
- data set $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^N$
- build a function $f : \mathcal{X} \to \mathcal{Y}$
- f must be able to predict the value of \hat{y} , given some \hat{x}

Different algorithms, methods and problems according to:

- the kind of **input** space \mathcal{X}
- \bullet the kind of output space ${\cal Y}$
- the choices made for the definition of function f
- the choices made for the **computation of function** *f*

Possible input spaces:

- $\mathcal{X} = numerical and/or attributes$
- $\mathcal{X} =$ logic representations
- $\mathcal{X} =$ some structured space (tree, graph, etc.)

Possible output spaces:

- $\mathcal{Y} = \{\pm 1\} \rightarrow$ binary classification
- $\mathcal{Y} = \{1, \dots, M\} \rightarrow \mathsf{multi-class\ classification}$
- $\mathcal{Y} = \Re \rightarrow \mathsf{regression}$
- $\mathcal{Y} =$ some structured space \rightarrow structured output

Classic problems

A very classic example: least-squares linear regression

•
$$\mathcal{X} = \Re^d$$

• $\mathcal{Y} = \Re$
• $\hat{y} = f(x) = \sum_{k=1}^d \alpha_k x_k$
• $\alpha = \arg \min \sum_{i=1}^N (\hat{y}_i - y_i)^2$



Unsupervised learning

Setting:

- we are given **no supervision**, just data
- we may not even know the task to perform on such data

So... Why is it useful...?

- Cluster data, find (frequent) patterns
- Identify most important features
- Reduce data dimensionality (encoding/compression)



Figure source: Wikipedia

Supervised learning

- ☺ labels are very useful
- Generation to be learned clearly defined
- ⊖ labels can be very costly

Unsupervised learning

- insupervised data are everywhere
- 🙂 can extract the most useful information from data
- ${}^{igodoldsymbol{ imes}}$ worse performance for a highly specific task

Semi-supervised learning ?

A different paradigm: teacher giving rewards/penalties



Largely used in many contexts: robotics, agents, control, ...

Reinforcement learning

A great example: computers playing Atari (by Google DeepMind)



Figure source: Wikipedia

When we are given a problem and we build a ML system to solve it, it is crucial to know **how to assess its performance**.

We basically need to **count the errors** of our system... ...But this is not so trivial as one could expect !

Example

- We have to build a diagnosis system for a very rare pathology
- Our system correctly classifies examples 99.9% of the times
- Can we be happy with such a classifier ?

Performance measures (binary classification)



• Accuracy
$$A = \frac{TP+TN}{TP+TN+FP+FN}$$

• Precision $P = \frac{TP}{TP+FP}$
• Recall $R = \frac{TP}{TP+FN}$

• F-Measure
$$F_1 = \frac{2PR}{P+R}$$

Performance measures (multi-class classification)

	True Class		
	А	В	С
A Pred Class B C	TP (A)	FP (A) FN (B)	FP (A) FN (C)
	FP (B) FN (A)	TP (B)	FP (B) FN (C)
	FP (C) FN (A)	FP (C) FN (B)	TP (C)

• Accuracy
$$A = \frac{\sum_{i} TP_{i}}{\sum_{i} TP_{i} + FN_{i}} = \frac{\sum_{i} TP_{i}}{\sum_{i} TP_{i} + FP_{i}}$$

• Precision
$$P^i = \frac{TP_i}{TP_i + FP_i}$$

• Recall
$$R^i = \frac{TP_i}{TP_i + FN_i}$$

• F-Measure
$$F_1^i = \frac{2P_iR_i}{P_i+R_i}$$

If a classifier produces a **score** (or a **probability**) for each example, rather than just the class, one can compute:

- Recall-Precision Curve
- ROC (Receiver Operating Characteristic) Curve

The curves are obtained by varying the threshold for the positive class, by using the scores produced in output by the classifier.

For **Recall-Precision** curves, Precision (y-axis) is reported as function of Recall (x-axis).

For **ROC** curves, *FPR* is reported on x-axis, and *TPR* on y-axis:

TPR = True Positive Rate = Recall FPR = False Positive Rate = 1 - Precision

Performance measures (classification)



Computing area under the curves (software): http://mark.goadrich.com/programs/AUC/

- Mean squared error (MSE)
- Root mean squared error (RMSE)
- Mean absolute deviation (MAD)

$$MSE = \sum_{i=1}^{N} \frac{(\hat{y}_i - y_i)^2}{N}$$
$$RMSE = \sqrt{MSE}$$
$$MAD = \frac{1}{N} \sum_{i=1}^{N} |\hat{y}_i - y_i|$$

The performance of any machine learning system strongly depends on a set of **parameters**, whose values have to be chosen during the training phase.

The procedure through which we choose the best parameters for a machine learning system is called **model selection**.

A typical approach to model selection splits the data into:

- training set (or learning set)
- validation set
- test set

The **training set** is used to learn function f.

The **validation set** is used to measure the performance of the model during paramater selection.

The **test set** is used to measure the effective performance of the predictor on unseed data.

The data split **should maintain** the proportion among classes.

Split the data into K sets, named **folds**

In turn, each fold will act as **test set**, whereas the remaining folds will form the **training and validation sets**

K-fold cross validation

Training and validation sets are employed to select the model, whereas the test set is used to compute the performance



The procedure is repeated K times for all the folds



Statistics computed over the K folds are reported. Suppose to have the following results from a 3-fold cv:

- TP=5, TN=10, FP=2, FN=3
- TP=3, TN=12, FP=4, FN=1
- TP=8, TN=11, FP=0, FN=1

We have two possibilities:

- compute P, R, F₁ for each fold and then average (macro-average)
- sum up all TP, TN, FP, FN and compute a single P, R, F₁ (micro-average)

A machine learning system is usually trained to **minimize some cost (loss) function**, thus it should not be surprising that it is capable to have a low error on the examples seen during training !

Main drawback

One could learn **perfectly** the training set, while being completely **unable to generalize** across different examples !

This is called **overfitting** \rightarrow that is why we need cross-validation !

A first classifer: k-Nearest Neighbors

A very simple supervised classifier:

- use some **distance** to measure distance between examples
- predict the class of a given example as the most frequent **class** among the k nearest examples in the training set
- possibly compute a weighted voting (using distances)



Figure source: Wikipedia

Despite simplicity (no learning !), it may work well in practice...

- when dealing with a large training set
- when a distance measure is employed

... but beware of the following drawbacks:

- ullet when dealing with a large training set $igodoldsymbol{eta}$
- when dealing with high dimensional spaces

Wolpert & MacReady, 1997

Any two learning algorithms are equivalent when their performance is averaged across all possible problems

No single model that works best for every problem

- looking only at data is **not enough**
- a model needs some assumption to generalize
- all we know about data is what we observe (Hume)

Example

- two Boolean input features, one binary output class
- two examples are given: ((0,0),0) and ((1,1),1)
- how to predict output for the two missing cases ?

The **expected generalization error** of a learning algorithm can be **decomposed** into **bias/variance** terms:

$$Error = (E[f(x)] - y)^2 + Var[f(x)] + \sigma^2$$

Bias error due to:

• wrong assumptions of the learning algorithm (underfitting)

Variance error due to:

• large variations with small perturbations (overfitting)

Low bias \to accurate esitmate on average Low variance \to estimate not changing much w.r.t. training set

Bias-variance tradeoff

Bias-variance trade-off (or dilemma)

Procedures with increased flexibility to adapt to the training data (e.g., have more free parameters) tend to have **lower bias** but **higher variance**, and the other way round



Figure source: [Duda et al., 2000]

Which function is to be preferred ? Green or blue ?



Figure source: Wikipedia

Many approaches minimize a function composed of two terms:

$\min_f \sum_{i=1}^N V(f(\hat{x}_i), \hat{y}_i) + \lambda R(f)$

- V(f(x), y) is a loss function measuring how much f misclassifies the training examples
- *R*(*f*) is a **regularization term** that typically **penalizes the complexity** of *f*

Examples of regularization in case of $f(x) = w^T x$:

- $\|w\|_2^2 \to \mathsf{Tikhonov}$ regularization
- $\|w\|_1 o$ sparsity regularization
- . . .

Probably **the most important factor** for a machine learning application to succeed or fail:

- ullet features correlating well with the class o easy igodot
- \bullet class as a complex function of features \rightarrow tricky $\textcircled{\odot}$
- ullet raw data has no evidence of correlation with class ightarrow hard igodot

In the last case, **constructing** good features as a pre-processing step becomes the **crucial ingredient** of the application

One major aim of machine learning is to **feature learning** (a.k.a. **representation learning**) directly from data

A central question in AI

How do knowledge and information is represented in our mind ?

Symbolic approaches:

• reasoning as the result of formal manipulation of symbols

Connectionist (sub-symbolic) approaches:

• reasoning as the result of processing of interconnected (networks of) simple units

What is the solution ?

Connectionist vs. symbolic approaches

• Symbolic approaches have a high interpretability



toxic(m) :- doublebond(m,c1,c2), hydroxyl(c2), methyl(m)

• Connectionist approaches can be easily **distributed**, decisions are **smooth**, undertake a **graceful degradation**, and can easily handle **uncertainty and incompleteness** in data

What we will not cover in this course:

- Clustering
- Reinforcement learning
- Computational learning theory
- Genetic algorithms
- Bayesian learning
- Graphical models
- Active learning
- . . .

Introduction to Artificial Neural Networks

Artificial Neural Networks (ANNs) are one of the **most famous** and **long-standing** learning paradigms developed in AI:

- inspired by the architecture of human brain
- highly parallel and distributed computable units
- the archetype of **connectionist** model

Throughout the years, research in ANNs has alternated periods of great **excitement** and **delusion**...

 \ldots Currently, there is a huge excitement in the area ! \bigcirc

Biological Neural Networks



Figure source: Wikipedia

1943 — McCulloch and Pitts: the artificial neuron



Figure source: http://aishack.in/

Fixed weights, binary input/output !

1958 — Rosenblatt: perceptron



Weights can be learned, input/output not binary !

1969 — Minsky and Papert: limits of the perceptron

Even simple functions (e.g., XOR) cannot be learned... Only **linearly separable** problems can be solved !



Figure source: http://colorado.edu

Al Winter 😊

- 1974 Werbos: first ideas of backpropagation
- 1984 Hopfield: Hopfield Networks
- 1986 Rumelhart, Hinton, Williams: backpropagation 🙂



- Init the network with random weights
- For each example in a training set $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^N$ repeat:
 - compute a forward pass on the network
 - Propagate the errors backward from the output
 - update the weights
- Compute the error on the validation set
- Stop training when some criterion is met

The error function is usually a quadratic loss:

$$E(w) = \sum_{i=1}^{N} (y_i - o_i)^2$$

The output of neuron *j* is activated by a **sigmoid function**:

$$o_j = \sigma(net_j) = \sigma\left(\sum_{k=1}^n w_{kj}o_k\right)$$

 $\sigma(z) = rac{1}{1+e^{-z}}$



How to optimize the loss function ?

- **batch** optimization (update w_{ij} after each epoch)
- **stochastic gradient descent** (update *w_{ij}* after each example)
- **mini-batch** (update w_{ij} after a bunch of examples)

For each epoch (or example) *t*:

$$w_{ij}^t = w_{ij}^{t-1} - \eta \Delta w_{ij}$$

where:

$$\Delta w_{ij} = \frac{\partial E}{\partial w_{ij}}$$

and η is the learning rate

How to compute $\frac{\partial E}{\partial w_{ij}}$?

Use the **chain rule**:

$$\frac{\partial E}{\partial w_{ij}} = \frac{\partial E}{\partial o_j} \frac{\partial o_j}{\partial net_j} \frac{\partial net_j}{\partial w_{ij}}$$

(The activation function is required to be differentiable)

Example: for an output neuron, it is easy to compute:

$$\frac{\partial E}{\partial o_j} = \frac{\partial}{\partial o_j} \frac{1}{2} (y_j - o_j)^2 = o_j - y_j$$

Main drawbacks:

- guarantee to converge only to a local minimum
- problems with plateau regions of the error function

Several tricks to circumvent the problem:

- multiple restarts with different initializations
- use a momentum term to move even when gradient is zero

$$w_{ij}^{t} = w_{ij}^{t-1} - \eta \Delta w_{ij}^{t} - \mu \Delta w_{ij}^{t-1}$$

Training a neural network: tricks of the trade

How to setup:

- the number of epochs
- the number of layers
- the number of hidden units in each layer
- the learning rate

Given a network with a fixed architecture (parameters 2-3-4), the number of epochs is chosen following the **early stopping** principle



Training a neural network: tricks of the trade

- The **number of hidden layers**, until the recent "deep learning revolution", was typically 1 (2 at most)
- The number of hidden neurons should be chosen according to the validation error
- The **learning rate** has to be carefully chosen with a trial-and-error procedure (it is **problem-dependent** !)

Choosing the learning rate is tricky !

- too small: slow convergence
- too large: divergence (might miss the optimum)

Many approaches employ an **adaptive** learning rate:

- if last step was good \rightarrow increase
- if last step was poor \rightarrow **decrease**

Multi-class classification

Network architecture:

- one output node per class
- one-hot encoding of classes

Target 3 out of 5 classes \rightarrow 0 0 1 0 0 Target 5 out of 5 classes \rightarrow 0 0 0 0 1

Training a neural network: tricks of the trade

Categorical attributes

Consider for example some attributes of PhD students:

- Male/Female
- Nationality
- Name of M.Sc. University
- . . .

Need to expand the number of features:

• one-hot encoding (as for multi-class)

```
Value 3 out of 5 outcomes \rightarrow 0 0 1 0 0
Value 5 out of 5 outcomes \rightarrow 0 0 0 0 1
```

Training a neural network: tricks of the trade

Numerical attributes

Even numerical attributes need some pre-processing:

- different ranges
- different distributions

Need to encode and/or normalize:

- uniform scaling: $\hat{v} = \frac{v v_{min}}{v_{max} v_{min}} \rightarrow [0, 1]$
- normalization: $\hat{v} = rac{v-\mu}{\sigma}
 ightarrow$ zero mean and unit variance

To try some first experiments

- A simple tool to start with ANNs:
 - pyBrain: pybrain.org
- A collection of datasets:
 - UCI Machine Learning Repository: http://archive.ics.uci.edu/ml/