



# Mobile Systems M

Alma Mater Studiorum – University of Bologna  
CdS Laurea Magistrale (MSc) in  
Computer Science Engineering

Mobile Systems M course (8 ECTS)  
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## 02 – Mobile Ad Hoc Network (MANET) and Routing

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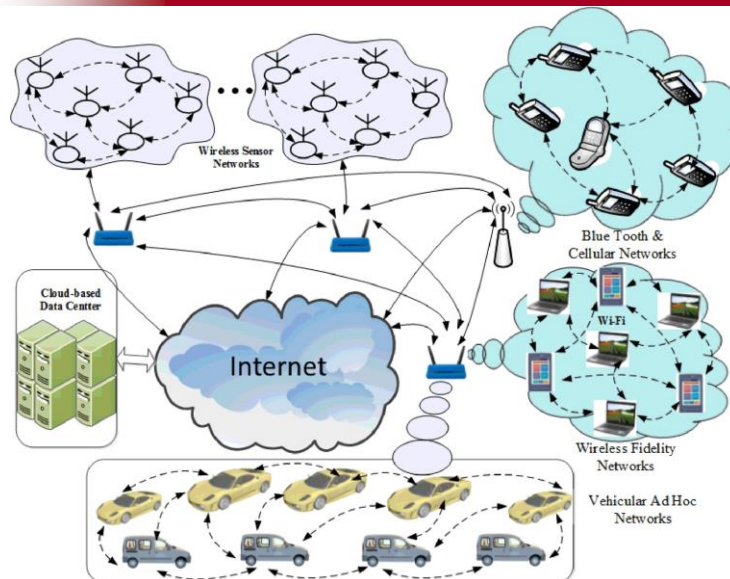
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## What is exactly an Ad Hoc Network?



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## Primary Features of Wireless Ad Hoc Networks

- ❑ **Created dynamically** (on-the-fly) to satisfy needs and reqs that are typically **temporary**
- ❑ **Immediate and highly reconfigurable deployment** (NO fixed infrastructure)
- ❑ High “volatility”
  - **Mobility, failures/faults**, node resources that vary over time
- ❑ Nodes with very differentiated features (**heterogeneity**)
- ❑ Nodes with **limited energy (battery-operated)**
- ❑ **Any node can play the role of potential router**
  - **Multi-hop communications**

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## Tech Challenges for Ad Hoc Networks

- ❑ Limited transmission range
- ❑ Broadcast nature of the wireless medium (e.g., hidden terminal)
- ❑ Packet loss due to transmission errors
- ❑ **Mobility**
  - **Modifications to routing and established paths due to mobility**
  - **Packet loss** induced by mobility
  - **Network partitioning** is possibly frequent
- ❑ Energy constraints
- ❑ Easy “snooping” of wireless transmissions (associated security issues)

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## Possible Application Areas for MANETs

But a **vast spectrum** of possible application areas :

- ❑ Personal Area Networking
  - Cellphones, laptops, wrist watches, human body sensors, ...
- ❑ Civil environments
  - Meeting rooms, stadiums, ships/planes groups, ...
- ❑ Military environments
  - War scenarios, realization of dynamic coalitions while in the war field, lack of infrastructure in enemy fields/areas
- ❑ Rescue/emergency operations
  - Search&rescue, police actions, firemen, ...
- ❑ Sensor and actuator networks
  - Groups of sensors/actuators embedded in the environment (e.g., smart home) or “scattered” in geographical wide area

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## Several Variants are Possible...

- ❑ Fully **symmetric** environments
  - Any node has the **same capabilities and responsibilities**
- ❑ **Asymmetric capabilities**
  - Different coverage ranges and differentiated **wireless** transmission techniques
  - Different **battery life**
  - Different **computing capabilities**
  - Different **mobility degrees** (e.g., speed ranges)
- ❑ **Asymmetric responsibilities**
  - Only some nodes can perform **packet routing**
  - Only some nodes play the role of **leader** for their neighbors (e.g., clusterheads)
- Differentiated **traffic characteristics**
  - Bandwidth, latency, reliability; unicast/broadcast/multicast/geocast

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## Several Variants are Possible...

- They can also **co-exist and cooperate** with infrastructure-based networks
- Different **mobility patterns**
  - People seated in waiting rooms (*limited mobility*)
  - Taxi cabs (*high mobility*)
  - Military movements (most of them are *clustered?*)
  - Personal area networks (also in this case, most movements are *clustered?*)
- **Mobility features**
  - Speed
  - **Predictability** (direction, pattern, triggers, ...)
  - **Uniformity or lack of uniformity** in the mobility of different cooperating nodes



## Routing in MANETs: Overview

First issue: ROUTING

- Why MANET routing is specifically hard and challenging?  
The answer to you ☺...
- **3 routing protocols**, described below
  - Dynamic Source Routing (**DSR**)
  - Ad hoc On-demand Distance Vector routing (**AODV**)
  - Greedy Perimeter Stateless Routing (**GPSR**)

And, in addition, some elements of **the more sophisticated TORA**



## How to Properly Perform Routing in MANETs?

- ❑ Usually ad hoc networks **involve mobile nodes**
  - Most relevant exception (only partial): Wireless Sensor Networks (WSN)
  - Thus, mainly Mobile Ad hoc NETWORKS (MANETs)
- ❑ **Several routing protocol proposals in the related literature**
  - Some of them specifically designed for MANETs
  - Other ones adapted from existing protocols, previously proposed for usage in wired networks
- ❑ **No single protocol has demonstrated to be optimal** in any possible deployment environment and scenario
  - Some proposals also towards the development of **adaptive protocols**



## Why Routing is Different in MANETs?

- ❑ **Host mobility**
  - Link failure/repair operations in response to mobility may have different characteristics if compared with management operations reacting to other problems
- ❑ **Frequency (rate) of link failure/repair operations** may be high in the case of high mobility
- ❑ Need of exploiting **new criteria for performance evaluation**, for example
  - **Stability** of routing paths **depending on mobility**
  - **Energy consumption**



## MANET Routing Protocols

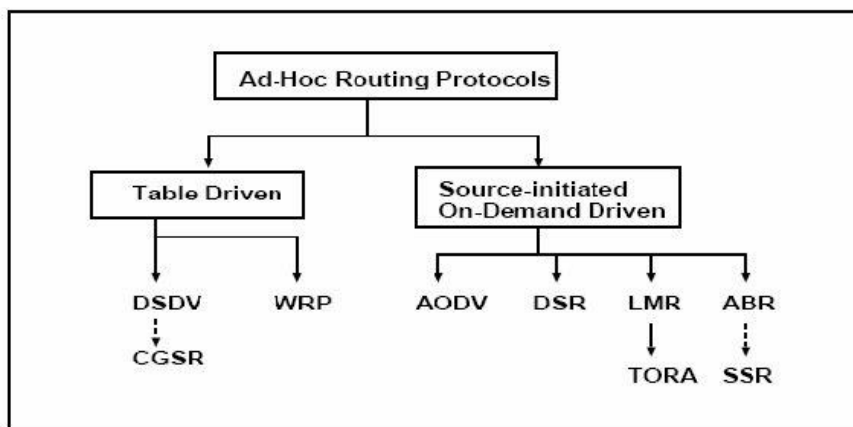
- ❑ **Proactive protocols**
  - **Maintain valid routes independently on ongoing traffic**
  - Generally, minor latency and greater overhead
  - Traditional routing solutions such as link-state and distance-vector are proactive
- ❑ **Reactive protocols**
  - **Maintain valid routes only if needed** (on-demand)
- ❑ **Geographic protocols**
  - Usage of knowledge of destination **location** to perform forwarding
- ❑ **Hybrid protocols**

Which is the best approach? *It depends on traffic and mobility patterns*

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## Just for curiosity, other taxonomies are more than possible



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## Trivial Solution: Flooding

### □ **Advantages**

- Simplicity
- More efficient when **transmission frequency is very low** (no need of discovery/maintaining valid routes or paths)
- **Potentially higher reliability** (exploitation of *multiple paths*)
- More suitable for **high mobility patterns**

### □ **Disadvantages**

- Potentially high overhead
- Potentially low reliability (broadcast exploitation, **no reliable broadcast** always available at low-layers of the employed wireless connectivity protocol)

Some protocols use **flooding for control packets**, typically for routing discovery (overhead mortgaged over the successive longer sequence of data transmissions)



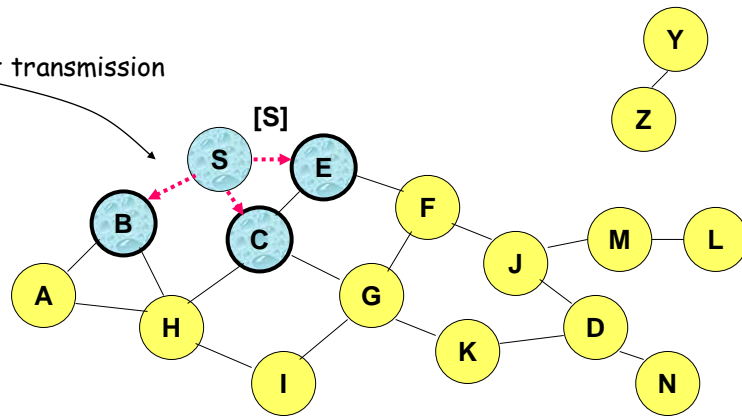
## Dynamic Source Routing (DSR) (Johnson&Maltz, CMU, 1996)

- **Source routing**: it is the source that tries to establish and embeds **the whole path** (from source to destination) in the exchanged packets
- How does the source determine the valid path in DSR?
  - When a node S is willing to send a packet to node D, but it does not know yet a valid route to D, **S starts an operation of route discovery**
    - S performs **flooding of a Route Request** (RREQ) packet
    - Any node **appends its own identifier** to the packet header when forwarding the received RREQ packet



## Route Discovery in DSR (1)

Broadcast transmission



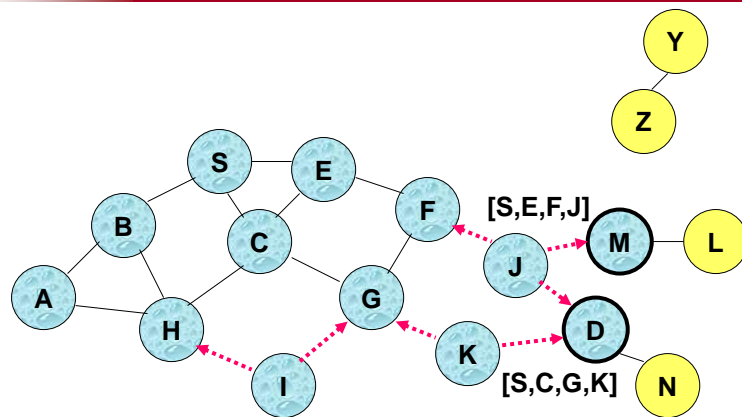
.....→ Represents RREQ transmission

[X,Y] Represents the list of identifiers appended to RREQ

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## Route Discovery in DSR (2)



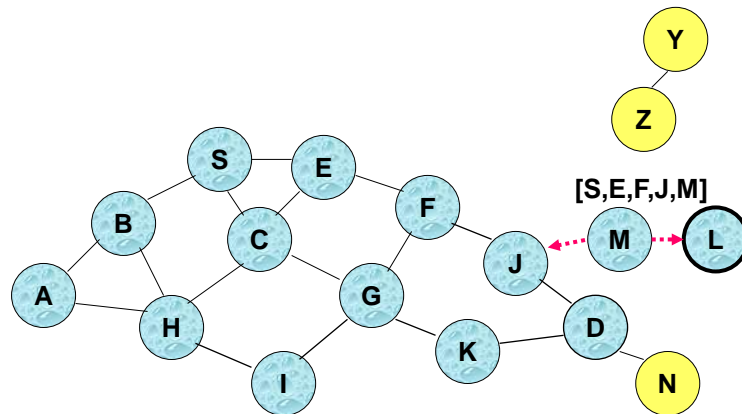
- Nodes J and K both perform RREQ broadcast to node D
- Since nodes J and K may be *hidden nodes* the one of the other, their *transmissions may be colliding*

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## Route Discovery in DSR (3)



Node D **does not perform forwarding** of the RREQ packet because it realizes to be the **desired destination** for the route discovery operation

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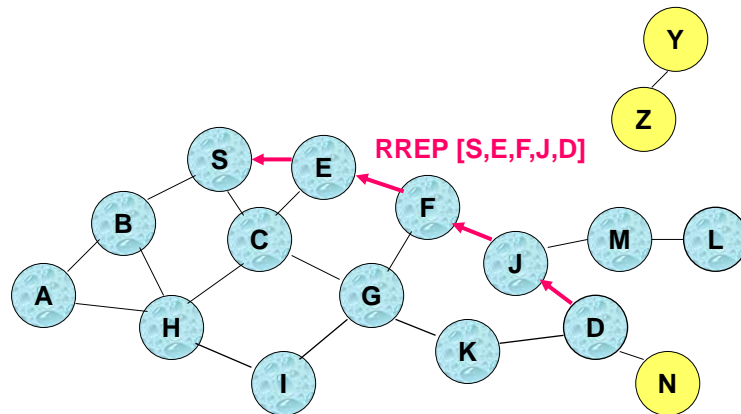
## Route Reply in DSR

- ❑ Destination D, once received the first RREQ packet, sends a reply packet called **Route Reply (RREP)**
- ❑ RREP is sent on the **inverse path** wrt the one contained in the received RREQ packet
- ❑ RREP **includes data about the path** from S to D, i.e., the one used by RREQ to reach D

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## Route Reply in DSR: Example



← Represents the RREP control message

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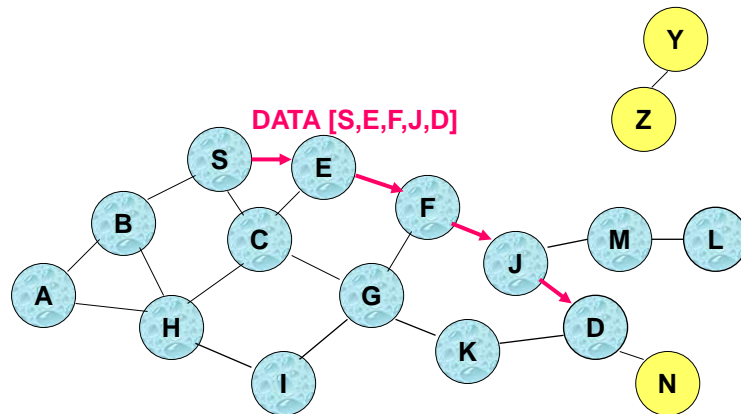
## How to Perform Data Routing in DSR?

- ❑ Node S, after receiving RREP, can **cache the path** included in the RREP message
- ❑ When node S is willing to send a data packet to D, **the whole routing path is included in the packet header** (this is the reason why this is called source routing)
- ❑ **Intermediary nodes use the source route** included in the data packet to **determine to which node the packet has to be forwarded**

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## Data Messages in DSR



*The packet header size grows with the path length*

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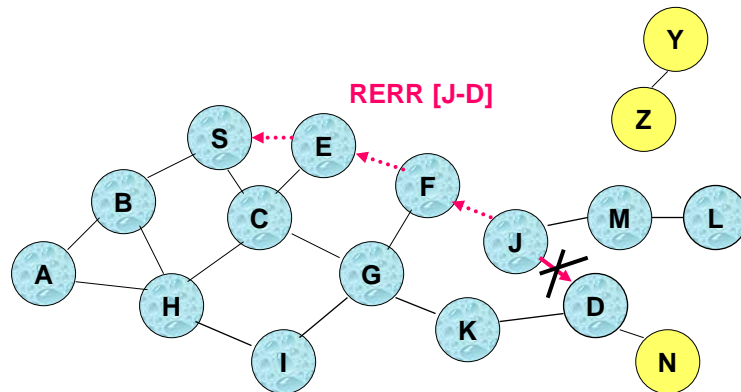
## Path Caching in DSR

- ❑ **Path caching** (or *route caching*) is an add-on optimization
- ❑ Any node can perform caching of new paths that it happens to discover, in any possible way
- ❑ Advantages
  - **Accelerates** the route discovery process
  - **Reduces** the **RREQ propagation** process
  - Helps the exploitation of additional alternate paths
- ❑ Disadvantages
  - **Invalid caches** (*stale caches*) may negatively affect on the overall performance
    - How to invalidate the distributed caches?

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## Route Error (RERR)



- **J sends an RERR packet to S** along the JFES path when its forwarding of a data packet from S to D fails, e.g., due to node mobility
- Nodes that listen to the RERR packet can update their path cache and **remove the JD link**

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## DSR: Pros and Cons

- **Advantages**
  - Paths are maintained only among nodes that need to communicate (reduced overhead)
  - Caching can reduce the overhead associated with routing discovery
  - Each discovery can lead to the determination of **multiple paths** to destination because of intermediaries that reply based on local caches
- **Disadvantages**
  - **Growth of packet header size**
  - **RREQ flooding**
  - Necessary mechanisms to avoid RREQ collisions among neighbors
  - Increase of channel conflicts when sending RREP (**RREP storm issue**; overhearing and local decision based on shortest path)
  - RREPs that use **stale cache** (affecting other caches in cascading)
    - Static timeout for caching, or
    - Adaptive timeout based on expected mobility, statistics about link usage, probability of link failure

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## Ad hoc On-demand Distance Vector (AODV)

(Perkins&Royer, Sun&UCSB, 1999)


DSR may lead also to **large-size headers** and consequent performance degradation

- In particular, when typical payloads are small
- ❑ **AODV** tries to improve the DSR efficiency **by maintaining lightweight routing tables, suitable for MANET nodes**
  - Data packets do not include path info at all
- ❑ AODV maintains the positive feature of DSR that **paths are stored only on the nodes that need to communicate** (by need)



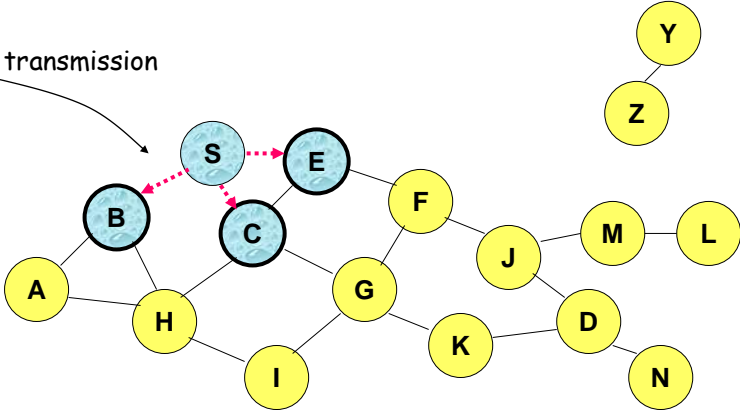
## AODV: Basic Idea

- ❑ **Route requests (RREQ) are forwarded similarly** to analogous packets in **DSR**
- ❑ When a node performs re-broadcasting of a RREQ packet, it initializes and starts an **inverse path that is directed** to the source node
- ❑ When the target destination receives an RREQ, it replies with a **Route Reply (RREP) packet**
- ❑ **RREP travels along the inverse path that is configured during the forwarding chain** of RREQ and **consequently configures the entries of the routing tables** only of the **traversed nodes**



## RREQ/Reverse Path Setup in AODV (1)


Broadcast transmission



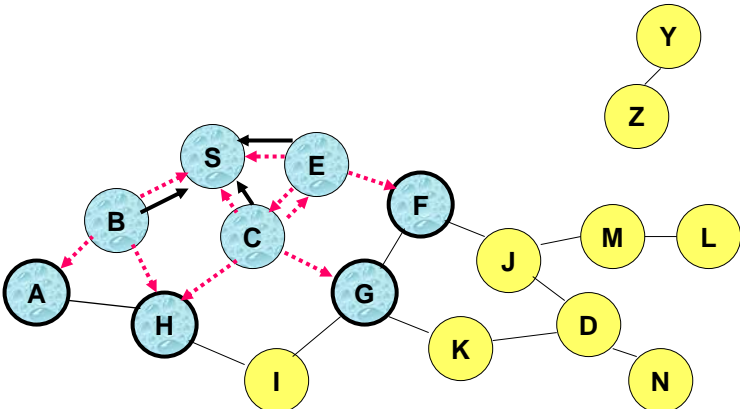
.....> Represents the RREQ transmission

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## RREQ/Reverse Path Setup in AODV (2)



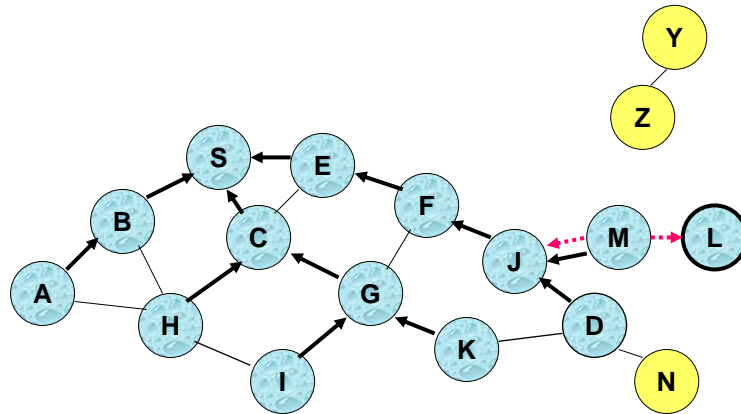
← Represents the links for the inverse path  
Backpointers are stored over the path nodes

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## RREQ/Reverse Path Setup in AODV (3)

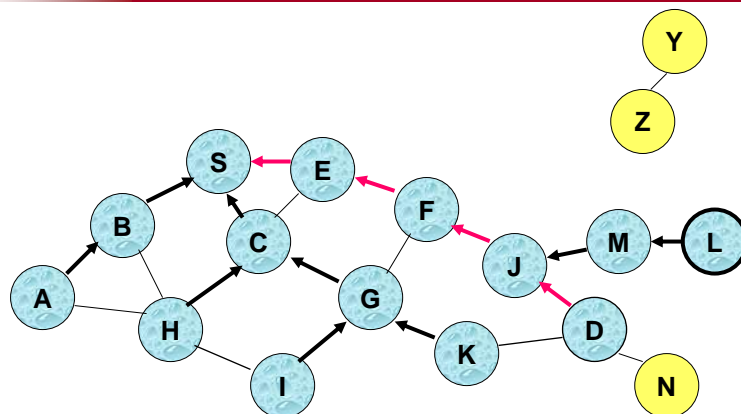


D does NOT perform RREQ forwarding because it is THE destination of RREQ

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## Route Reply in AODV



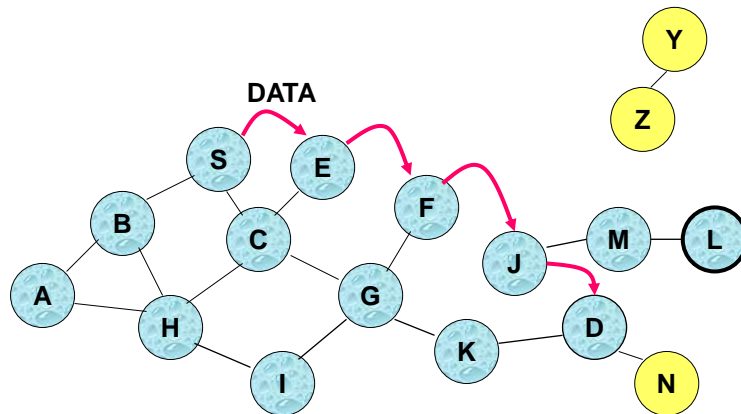
← Represents the link on the path used by RREP

Forward links are configured when the RREP packet passes through the inverse path

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## Data Transmission in AODV

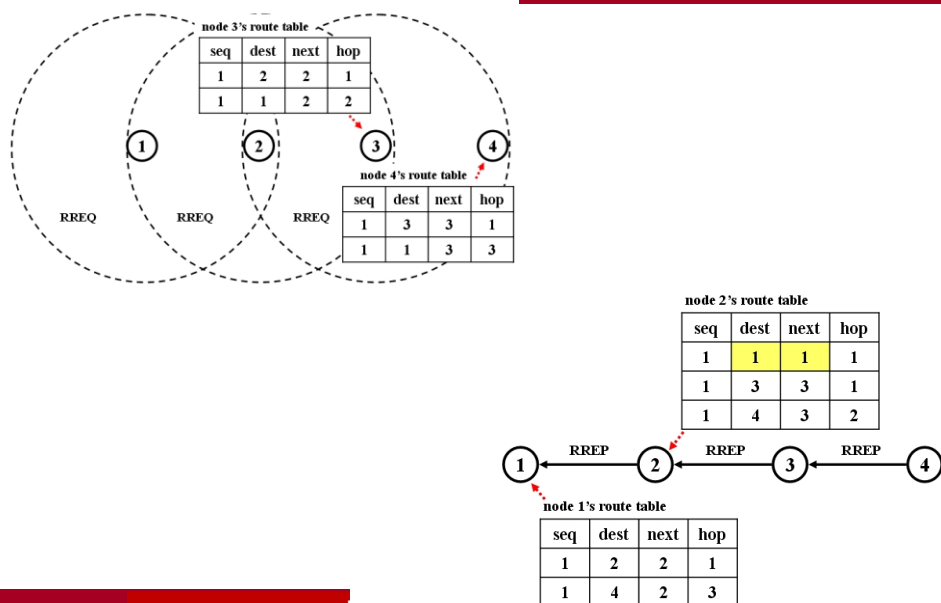


- The entries of the local routing tables are used to perform forwarding of data packets
- Differently from DSR, the path is not included in the header

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## Examples of AODV Routing Tables



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## Timeout

- ❑ Any entry of a routing table that includes an **inverse path is discarded after a given timeout**
  - Why? If **RREQ did NOT get to reach its destination, or if RREP did NOT correctly return back**, the related entry would occupy local memory in a completely useless way
  - **Timeout must be sufficiently long** to allow **RREP packets to return back**
- ❑ Any entry of a routing table that includes a **forward path** is removed if not used for a given interval called **active\_route\_timeout** (longer than the timeout for inverse paths)
  - Why? The path may **become invalid in short time** in highly mobile networks

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## Reporting of non-usable Links

- ❑ **A neighbor node is considered active** for one entry in the routing table if **one of its packets has been forwarded by using that entry** in the last **active\_route\_timeout** time interval
- ❑ When a **link** towards a next node included in the routing table **fails**, all **active neighbors are informed**
- ❑ A node generates **RERR in response to a broken path** to destination D
  - When S receives RERR, it starts a **new route discovery process** towards D

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## In addition: Link Failure Detection

- ❑ **Hello messages**: neighbor nodes periodically exchange alive messages
- ❑ **Lack of hello messages** is used as an indication of possible **fault/failure of a link**
- ❑ Alternatively, **the lack of a series of received ACKs at the MAC layer** can be used as an indication of probable link failure (*cross-layer monitoring*)



## How to Limit Flooding during the Phase of Route Discovery?

- ❑ Optimization: **gradual expansion of the search, ring shaped**
- ❑ RREQ messages are sent initially with **limited TTL**, in order to limit their propagation
  - DSR also may exploit (and several versions of it do that) a similar optimization
- ❑ If no RREP message is received, then the approach is to **try again with larger TTL**
  - Sending of a new RREQ

Therefore, we are looking for a more balanced **tradeoff among which factors?**



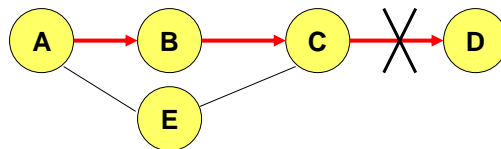
## AODV – Optimization

- ❑ **Possible additional optimization:** an intermediate node with a route to D can reply to RREQ
  - Faster operation
  - Decreases the issue of route request flood
- ❑ This optimization can cause loops in presence of link failures

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## AODV: Routing Loops



- ❑ Assume that link C-D fails and node A does not know about it (RERR packet from C is lost)
- ❑ C performs a route discovery for D
- ❑ Node A receives the route request (via path C-E-A)
- ❑ Node A replies, since A knows a route to D via node B
- ❑ **Results in a loop: C-E-A-B-C**

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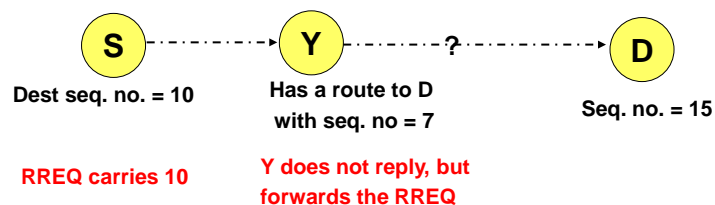


## AODV: Sequence Numbers

- Each node X maintains a **sequence number**
  - acts as a time stamp
  - incremented every time X sends any message
- Each route to X (at any node Y) also has X's sequence number associated with it, which is Y's latest knowledge of X's sequence number
- **Sequence number relates to 'freshness' of the route** – higher the number, more up to date is the route



## Use of Sequence Numbers in AODV

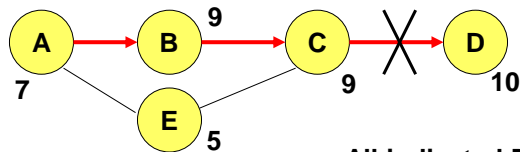


**Loop freedom:** intermediate node replies with a route (instead of forwarding request) only if it has a route with a higher associated sequence number



## AODV: Avoidance of Loops

DSN = Destination Sequence Number



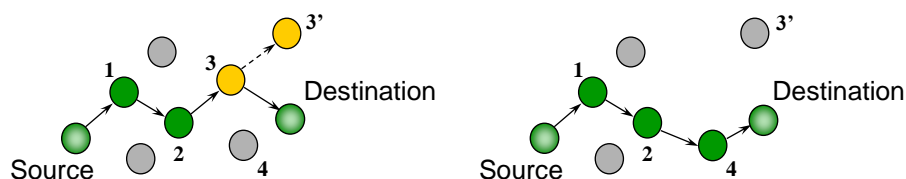
All indicated DSNs are for D

- ❑ Link failure increments the DSN at C (now is 10)
- ❑ If C needs route to D, RREQ carries the DSN (10)
- ❑ A does not reply as its own DSN is less than 10

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## Mobility-related Path Maintenance



- ❑ Movement not along the active path triggers no action
  - If source moves, reinitiate route discovery
- ❑ When destination or intermediate node moves
  - upstream node of break broadcasts RERR messages
  - RERR contains list of all destinations no longer reachable due to link break
  - RERR propagated until node with no precursors for destination is reached

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## Greedy Perimeter Stateless Routing (GPSR; Karp&Kung, Harvard, 2000)

**Geographic routing exploits location information** to facilitate reaching the destination

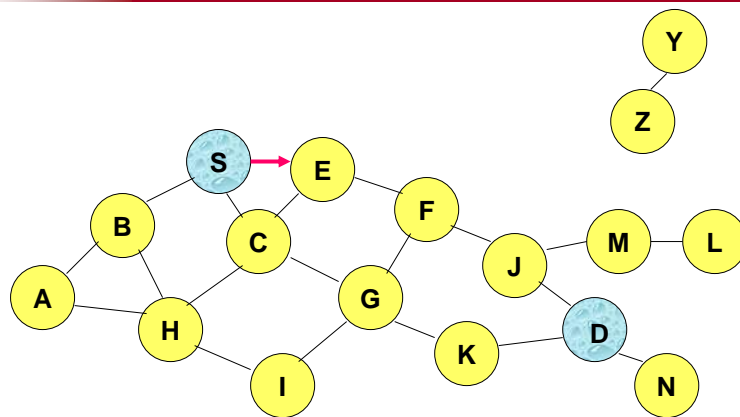
- **Assumption#1:** *source node knows the destination location*
- **Assumption#2:** nodes maintain *lists of neighbor nodes and their locations*
  - Need to include *location info in hello messages* (beacons) that are periodically exchanged

**Two schemes for data forwarding:**

- **Greedy forwarding:** data are sent to the neighbor node that is estimated as the closest one towards the destination (usage of only the location info of neighbor nodes for data forwarding)
- If **greedy forwarding fails**, switch to a different scheme, i.e., **perimeter forwarding**



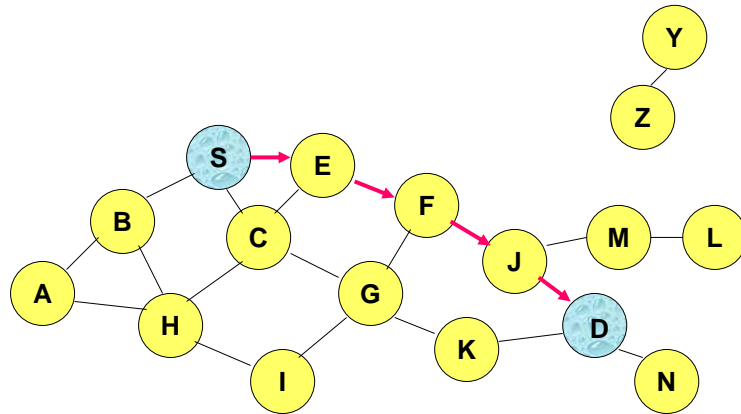
## Greedy Forwarding (1)



E is the S's neighbor that is closest to D  
("closest" in terms of Euclidean distance)



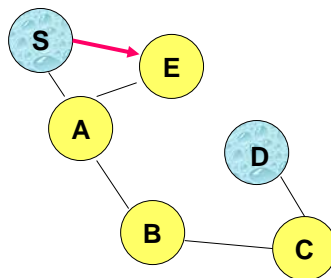
## Greedy Forwarding (2)



F is the E's neighbor node closest to D  
J is the F's neighbor node closest to D



## Possible Failures in Greedy Forwarding



In the case that E is not in the coverage range of D  
(assumption of the figure)

*No node among the E's neighbors is closer to D than E*

**Forwarding failure!**

**But a useful path would exist: [S, A, B, C, D]**



## Perimeter (Face) Forwarding

- It can ***always reach a destination if a useful valid path exists***
  - Route ***around the so-called “holes”***
- Each node calculates ***Relative Neighborhood Graph (RNG) or Gabriel Graph (GG)***
  - RNG is a ***non-directed graph*** defined on a set of points in the Euclidean plane that are compliant with this constraint: connecting two points A and B with an arc ***if and only if there is no point C that is closest to both A and B (C-to-A and C-to-B distances minor than A-to-B distance)*** - G. Toussaint, 1980
- ***RNG is traversed*** by using the right-hand rule
  - Basically, the idea is of ***visiting the nodes that determine the perimeter*** around a hole



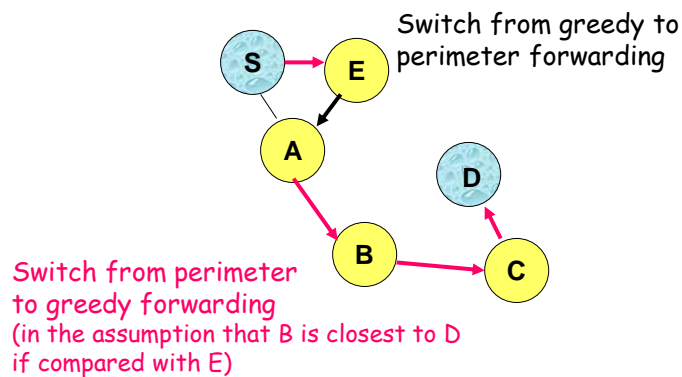
## Perimeter (Face) Forwarding

- During graph traversing, if a packet meets a node that is closest to destination if compared with the node where greedy forwarding had failed, ***the decision is to operate a new switch towards greedy forwarding***
- ***We can have loops*** if perimeter forwarding is used and whenever the destination is not reachable
  - GPSR is capable of detecting the situation and of discarding the involved packet





## Example



## Temporally Ordered Routing Algorithm (TORA)

TORA is proposed to operate in a **highly dynamic** mobile networking environment

- ❑ **Highly adaptive, loop-free, highly distributed**
- ❑ Based on the concept of **link reversal**

Key design concepts of TORA:

- ❑ **Localization of control messages** to a very small set of nodes **near the occurrence of a topological change**
- ❑ To this purpose, nodes need to maintain **routing info about neighbors**
- ❑ The **height metric** is used to model the routing state of the network

Three basic functions:

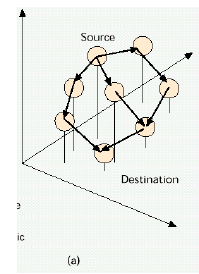
- ❑ **route creation**
- ❑ **route maintenance**
- ❑ **route erasure**



## Temporally Ordered Routing Algorithm (TORA)

During route creation and maintenance, nodes establish a Directed Acyclic Graph (DAG)

- ❑ **A logical direction** is imposed on links towards destination
- ❑ **Source-initiated**
- ❑ Provides **multiple routes** for any desired source/destination pair
- ❑ Starting from any node in the graph, a destination can be reached by **following the directed links**
- ❑ **Highly adaptive, efficient, scalable, distributed algorithm**
- ❑ **Multiple routes from source to destination**



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## TORA Major Tasks

Three major tasks

- ❑ Route creation – query (QRY) and update (UPD) packets
- ❑ Route maintenance
- ❑ Route erasure – broadcast of clear packet (CLR)

Using **unique node ID and unique reference ID for packets**

### 1) Route creation: demand-driven «query/reply»

Performed only when a node requires a path to a destination but does not have any directed link

- ❑ A QRY packet is flooded
- ❑ An UPD packet propagates back if routes exist

### 2) Route maintenance: «link reversal» algorithm

- ❑ React only when necessary
- ❑ Reaction to link failure is **localized in scope**

### 3) Route erasure

A CLR packet is flooded to erase invalid routes

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## TORA Metrics

- ❑ **Assigns a reference level (height) to each node**
- ❑ **A local DAG is maintained for each destination**
- ❑ **Synchronized clock** is relevant, accomplished via GPS or a dedicated protocol such as Network Time Protocol (NTP)

Timing is an important factor in TORA because the «height» metric is dependent on the logical time of a link failure

- ❑ Logical time of a link failure
- ❑ The unique ID of the node that defined the new reference level
- ❑ A reflection indicator bit
- ❑ A propagation ordering parameter
- ❑ The unique ID of the involved node

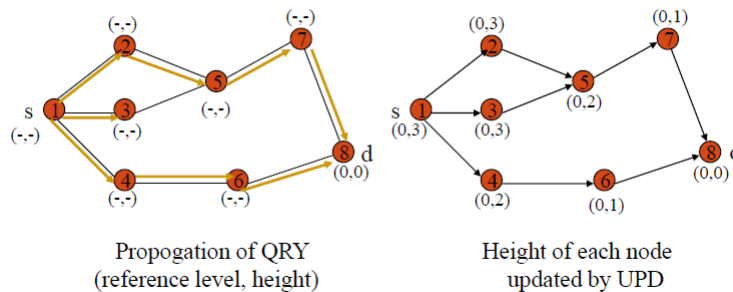
**Adjust reference level to restore routes on link failure**

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## Temporally Ordered Routing Algorithm (TORA)

- Route creation of TORA

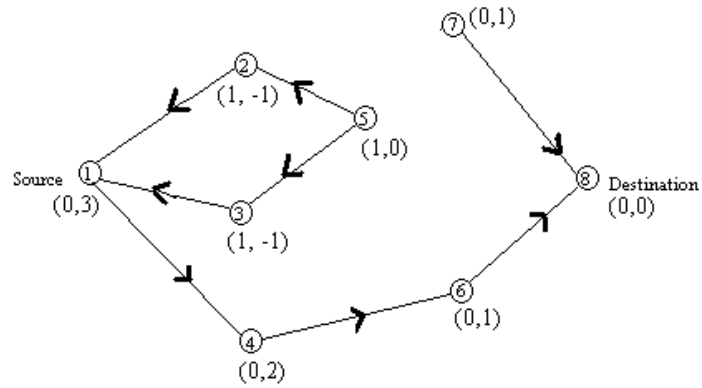


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## Temporally Ordered Routing Algorithm (TORA)

### Route creation

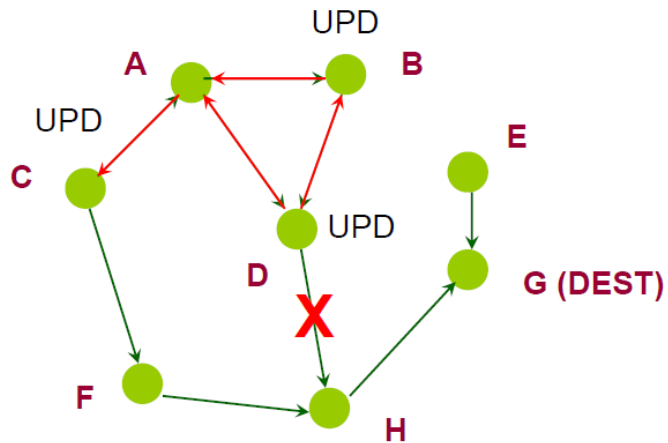


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## Temporally Ordered Routing Algorithm (TORA)

- Route maintenance

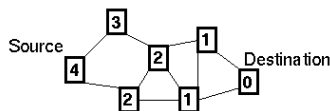


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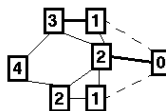


## Temporally Ordered Routing Algorithm (TORA)

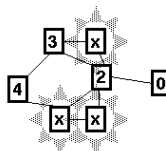
**Step 1**  
The network has converged.



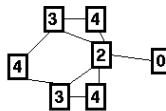
**Step 2**  
Some of the mobile nodes move, breaking links and forming new ones.



**Step 3**  
The nodes react to the new topology and adjust their height.



**Step 4**  
The network converges with a directed graph. Notice how the changes were localized.



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## Temporally Ordered Routing Algorithm (TORA)

In summary...

### **Advantages:**

- ❑ **Less control overload** – by limiting the control packets for route **reconfiguration to a small region**

### **Disadvantages:**

- ❑ Local reconfiguration of paths **results in non-optimal routes**
- ❑ Concurrent deduction of partitions and subsequent deletion of routes could **result in temporary oscillations and transient loops**

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## Moreover, many other MANET routing algos in the literature...

Think about optimizations that stem from

- ❑ Application requirements
- ❑ Most probable characteristics of deployment scenarios
- ❑ Rate between mobility&dynamicity vs communication rate
- ❑ Which information assumed to be known at participating nodes?
- ❑ Which node coordination and associated overhead?
- ❑ How much proactive? How much reactive?
- ❑ How much optimistic? How much pessimistic?



## For instance: Multi-hop Routing vs. Energy Consumption

- ❑ Energy consumption to transmit a packet:
  - Constant cost to power on the circuitry
  - Proportional to packet size
  - Proportional to distance \* distance
- ❑ Multi-hop routing can **reduce the consumption** of energy (the consumed energy is basically proportional to distance \* distance) but this can generate non-negligible **latencies**
- ❑ Which per-hop distance?
  - Too short => the dominant part of the energy cost is for powering on the circuitry
  - Too large => the dominant part is for packet transmission; **reduction of re-usability of bandwidth in space**; overhead for scheduling because the number of nodes at 1-hop-distance grows



## A short Parenthesis on Clustering

### Clustering (grouping) to *decrease resource consumption*

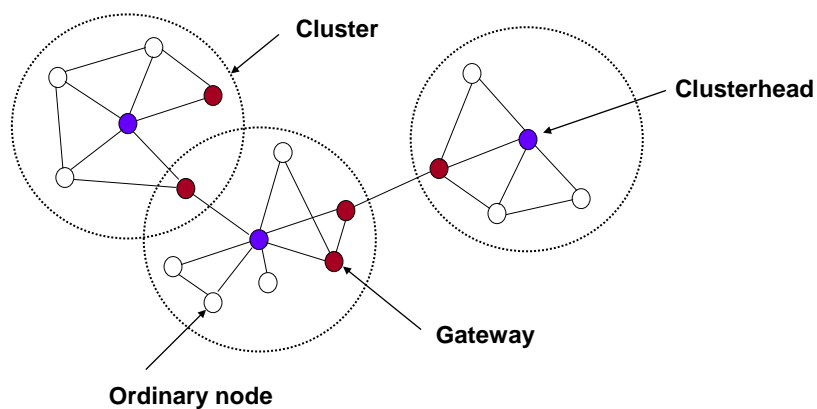
- ❑ Split the network in **clusters (groups)**, each of them including an “analogous” number of nodes
- ❑ **Clusterheads** are the **natural backbone** also in order to perform routing
- ❑ **Optimal clustering is an NP-complete problem**
- ❑ Very relevant: anyway mobility tends to **degrade the optimality of the determined clustering**

Specific usefulness for sensor networks: to combine “cluster-level readings” into a single data packet (*data aggregation*)

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## Clustering as a Routing Backbone



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## Very shortly: Clustering Examples

### LEACH

- ❑ **Local decision** if a node should serve as clusterhead or not (random number choice and completely local election)
- ❑ Any non-clusterhead node performs overhearing and **selects the closest clusterhead**
- ❑ The clusterhead role **is periodically re-assigned (node rotation)** to balance energy consumption
- ❑ **Communication is first to clusterhead, then to cluster members**
- ❑ **No guarantee of optimality in clustering determination**

### HEED

- ❑ **Residual energy** to consider in the clusterhead election
- ❑ Clusterheads are elected after an iterative protocol:
  - A node announces its **intention and cost** as a clusterhead
  - Any non-clusterhead node selects its candidate with minor cost by following a probabilistic metric, possibly choosing itself



## Weighted Clustering Algorithm (WCA) (Chatterjee et al., 2002)

- ❑ A clusterhead can **ideally support  $n$  nodes**
  - Ensures efficient MAC functioning
  - Minimizes delay and maximizes throughput
- ❑ A clusterhead uses **more battery power**
  - Does extra work due to packet forwarding
  - Communicates with more nodes
- ❑ A clusterhead should be **less mobile**
  - Helps to maintain same configuration
  - Avoids frequent WCA invocation
- ❑ A **better power usage with physically closer nodes**
  - More power for distant nodes due to signal attenuation





## Is Wi-Fi Direct a MANET technology?

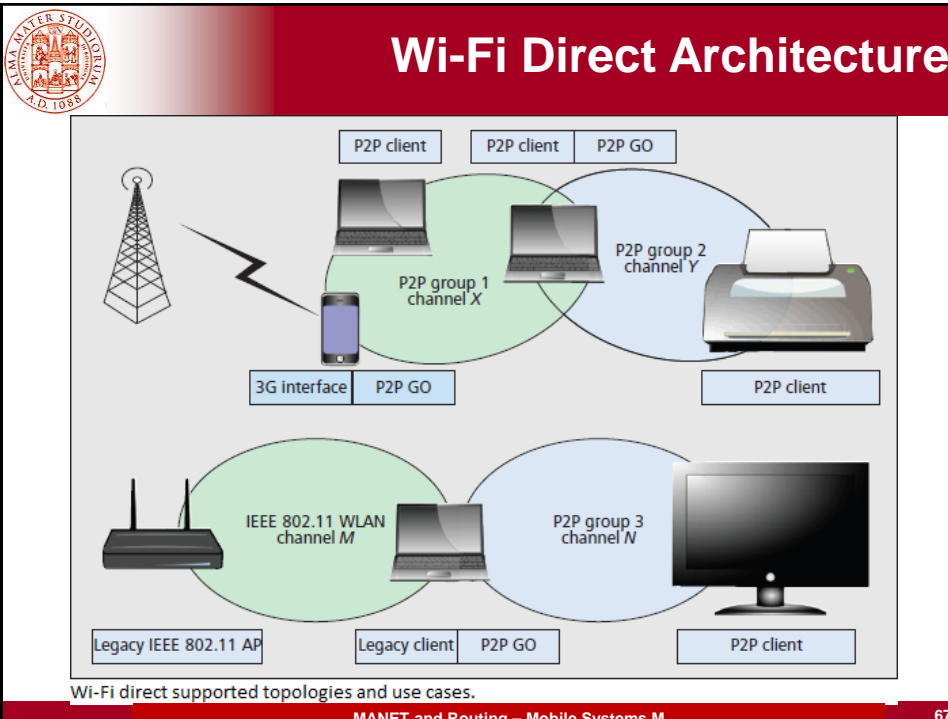
Given our current understanding of MANET, let us go back to Wi-Fi Direct...

- ❑ In a typical Wi-Fi network, client scans and associate to wireless networks available, which are created and announced by Access Points (AP)
- ❑ **Wi-Fi Direct allows specifying these roles as dynamic**, and hence a Wi-Fi Direct device has to implement both the role of a client and the role of an AP
- ❑ These roles are therefore **logical roles that could even be executed simultaneously by the same device**, this type of operation is called **Concurrent mode**



## Wi-Fi Direct Architecture

- ❑ Wi-Fi Direct devices communicate by **establishing a P2P group**
- ❑ The **device implementing AP-like functionality** in P2P group is referred to as the **P2P Group Owner (P2P GO)**, and device acting as client are known as P2P clients
- ❑ Once P2P group is established, other P2P clients can join the group as in a traditional Wi-Fi network
- ❑ When the device acts as **both as P2P client and as P2P GO, the device will typically alternate between the two roles by time-sharing the Wi-Fi interface**
- ❑ Like a traditional AP, a P2P GO announces itself through beacons, and has to support power saving for its associated clients



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## Wi-Fi Direct Architecture

- ❑ Only **the P2P GO is allowed to cross-connect** the devices in its P2P group to **an external network** (e.g., mobile in the previous figure)
- ❑ **This connection must be done at network layer**, typically implemented using Network Address Translation (NAT)
- ❑ **Wi-Fi direct does not allow transferring the role of P2P GO within the group**
- ❑ If P2P GO leaves the P2P group then the group is broken down and has to re-established

**Parallel and comparison with Bluetooth scatternets?**

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## Wi-Fi Direct Group Formation

Three types of group formation techniques: **Standard**, **Autonomous**, and **Persistent** cases

Group Formation procedure involves two phases:

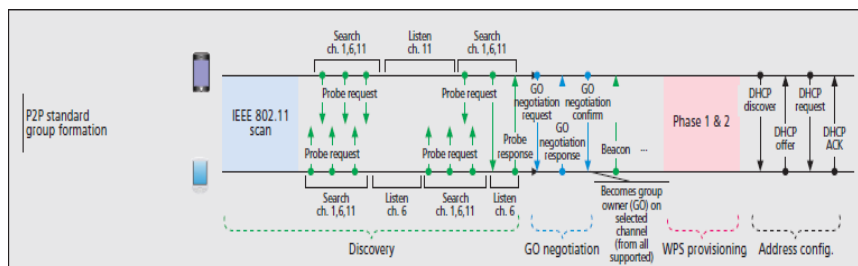
- Determination of P2P GO
  - **Negotiated** - Two P2P devices negotiate for P2P GO based on desires and capabilities
  - **Selected** - P2P GO role established at formation or at an application level
- Provisioning of P2P Group
  - Establishment of **P2P group session** using appropriate credentials
  - Using Wi-Fi simple configuration to exchange credentials



## Wi-Fi Direct Group Formation

**Standard:** P2P devices have to discover each other, and then negotiate which device will act as P2P GO

- Its starts by performing a traditional Wi-Fi scan, by means of which they can discover existing groups and Wi-Fi networks

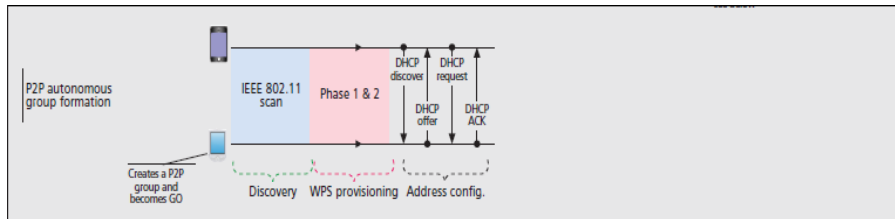


- To prevent conflicts when two devices declare the same GO Intent, a tie-breaker bit is included in the GO Negotiation Request, which is randomly set every time a GO Negotiation Request is sent



## Wi-Fi Direct Group Formation

**Autonomous:** a P2P device may autonomously create a P2P group, where it immediately becomes the P2P GO, by sitting on a channel and starting a beacon

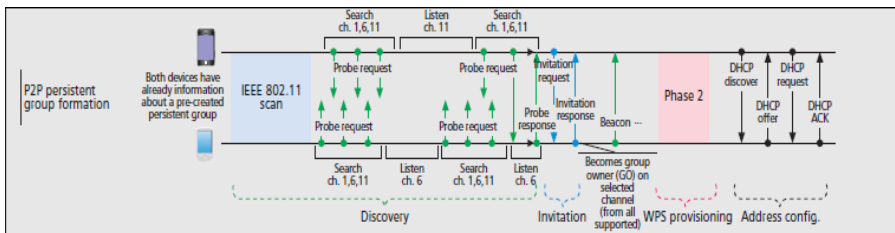


- ❑ **Other devices can discover the established group** using traditional scanning mechanisms
- ❑ As compared to previous case, **discovery phase is simplified** in this case as the device establishing the group does not alternate between states, and indeed no GO negotiation phase is required



## Wi-Fi Direct Group Formation

**Persistent:** a P2P device can declare a group as persistent, by using flag in the P2P capabilities attribute present in beacon frames



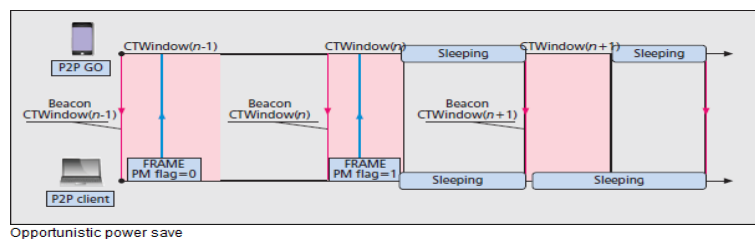
After the discovery phase, if a P2P device recognizes to have formed a persistent group with the corresponding peer in the past  
any of the two P2P devices can use the **Invitation Procedure to quickly re-instantiate the group**



## Wi-Fi Direct Power Saving

Wi-Fi Direct defines **two new power saving mechanisms**: the Opportunistic Power Save protocol and the Notice of Absence (NoA) protocol

**Opportunistic Power Save** protocol (OPS) allows a P2P GO to save power when all its associated clients are sleeping



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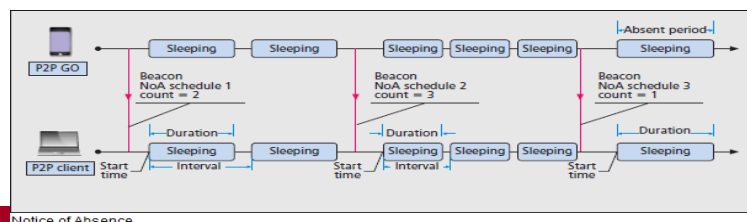
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## Wi-Fi Direct Power Saving

**Notice of absence** protocol (NoA) allows a P2P GO to announce time intervals, referred to as **absence periods**, where P2P Clients are not allowed to access the channel

- P2P GO defines a NoA schedule using four parameters:
  - Duration that specifies the length of each absence period
  - Interval specifying time between consec absence periods
  - Time that specifies the start time of the first absence period after the current Beacon frame
  - Count that specifies how many absence periods will be scheduled during the current NoA schedule



Notice of Absence

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## Wi-Fi Direct Security

- ❑ Wi-Fi Direct devices are required to implement **Wi-Fi Protected Setup (WPS)** to support a secure connection with **minimal user intervention**
- ❑ WPS allows establishing a **secure connection by introducing a PIN** in the P2P Client, or **pushing a button in the two P2P devices**
- ❑ Following WPS terminology, P2P GO is required to implement an internal Registrar, and the P2P Client is required to implement an Enrollee
- ❑ WPS operations consist of two parts
  - In the first part, the internal Registrar is in charge of generating and issuing the network credentials, i.e., security keys, to the Enrollee
  - In the second part, the Enrollee (P2P Client) disassociates and reconnects using its new authentication credentials



## Wi-Fi Direct: some Refs to Additional Material

### Optional additional readings:

- ❑ IEEE 802.11-2013 Standard, Device-To-Device communication with Wi-Fi direct: Overview and experimentation, 2007
- ❑ Wi-Fi Alliance, P2P Technical Group, Wi-Fi Peer-to-Peer (P2P) Technical Specification v1.0, December 2009
- ❑ Wi-Fi Alliance, Wi-Fi Protected Setup Specification v1.0h, Dec. 2006
- ❑ IEEE 802.11z-2010 - Wireless LAN Medium Access Control (MAC) and Physical Layer (PHY) specifications Amendment 7: Extensions to Direct-Link Setup (DLS)



## Other more Innovative Routing/Clustering Modes?

Under some **simplifying assumptions**, which can significantly facilitate how to solve the problem

Again **cross-layer** or **possible static assumptions** about given and determined deployment environments

For example, **content sharing** scenarios in sport events with very large public of attendants (Olympic stadium in Turin 2006) and widespread distribution of pictures/videos recorded by spectators

- to provide an **entertainment service**, e.g., small multimedia contents, dynamically discovered, to a **large public** of users **concentrated in space and in time**
- to maintain **content availability** notwithstanding ingress/exit of spectators from the targeted physical locality



## Dense MANET Assumption and Interaction with Application Layer

- Assumptions
  - **Dense MANET**
    - **Large number of devices co-located** in a physical area that is relatively small
    - **Node density** that is almost **invariant** over relatively long time intervals
  - **Replication and read-only replicas**
- Non-functional requirements
  - Low **overhead** → Lightweight and approximated protocols
  - High **scalability** → Complete decentralization
  - Sufficient **accuracy** → Protocol ending based on heuristics



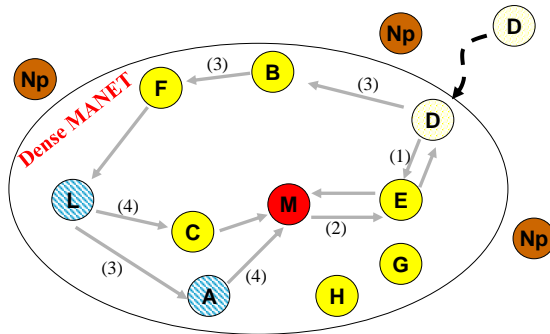
## Replication in Dense MANETs (REDMAN)

**Basic idea:** to *disseminate replicas* of resources of common interest and to *maintain the desired replication degree* independently from node mobility (unpredictable) in/out the targeted dense area

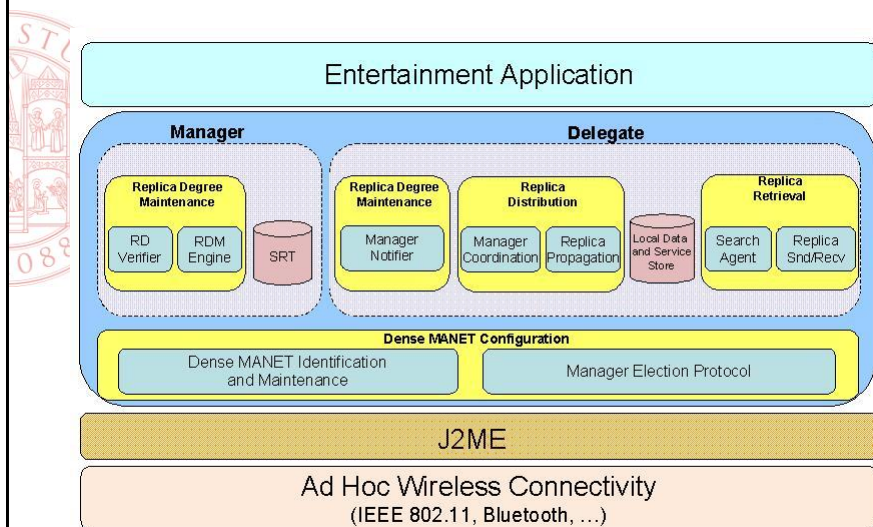
- **Delegates host replicas**, reply to retrieval requests, participate to dissemination
- **Managers:** responsible for maintaining the proper and desired replication degree

**Shared Resource Table**

| Resource Name            | Replication Degree | Probable Replica Placement |
|--------------------------|--------------------|----------------------------|
| Alberto Tomba's Picture! | 3                  | D, L, A                    |



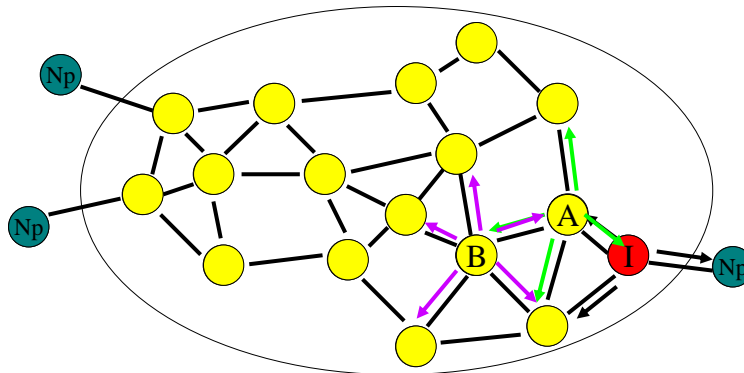
## Middleware Approach: Application-layer Management







## Issue: Identifying a Dense MANET

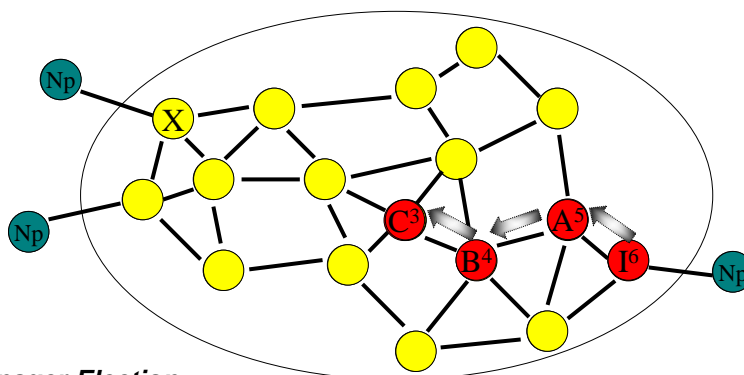


- Dense MANET if and only if  $\#Neighbors > Threshold$
- **Decentralized and lightweight protocol** in which any node **autonomously decides** its own belonging condition
- **Dynamicity**: lazy updates based on hello messages

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## Issue: Manager Election



### Manager Election

- Role is assigned to a node that is **topologically central**
- Lightweight solution, **no optimal placement** (priority is avoiding exhaustive search)
- Exploration strategy based on heuristics

### Dynamicity

- Reactive response: new determination of farthest nodes every  $T_r$
- Proactive response: new election every  $T_p \gg T_r$

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## Ending the Election Process

- **Optimal solution is considered to be found iff.**

1.  $currentINvalue = \lceil worstExploredValue / 2 \rceil$

- Alternatively, **heuristics:**

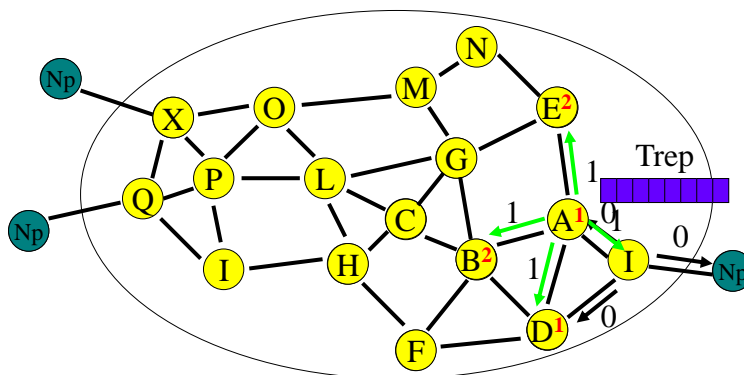
2.  $currentINvalue \leq worstExploredValue * DesiredAccuracy$

3. **maxConsecutiveEqualSolutions** have been explored without improving the current *bestValue*

Of course, **DesiredAccuracy** and **maxConsecutiveEquals** determine (approximatively) the quality of the solution achieved (quantitative indicator)

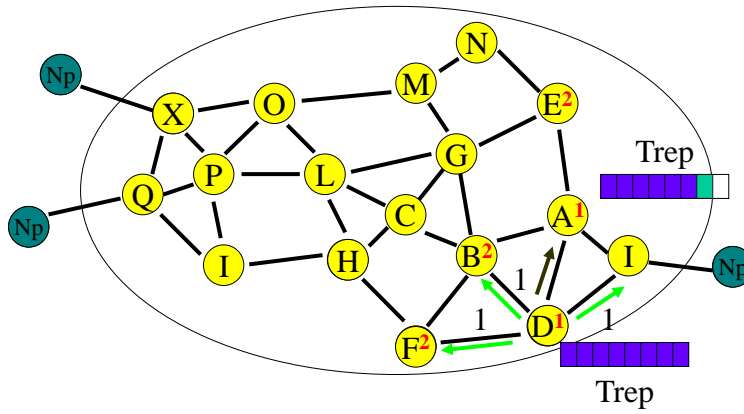


## Identifying the Farthest Nodes





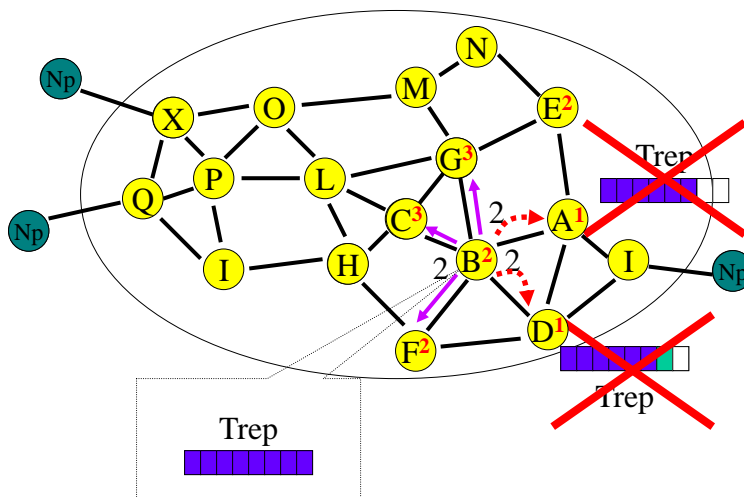
## Identifying the Farthest Nodes



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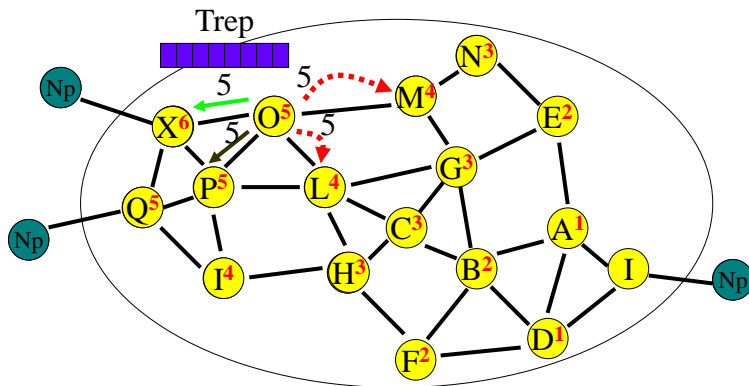
## Identifying the Farthest Nodes



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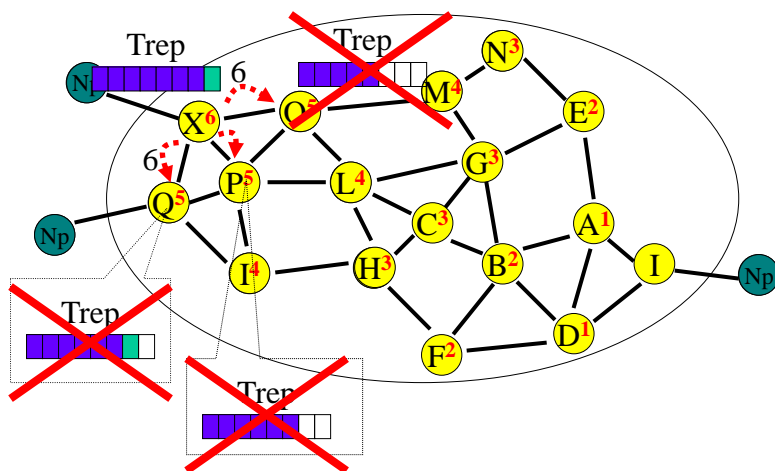
## Identifying the Farthest Nodes



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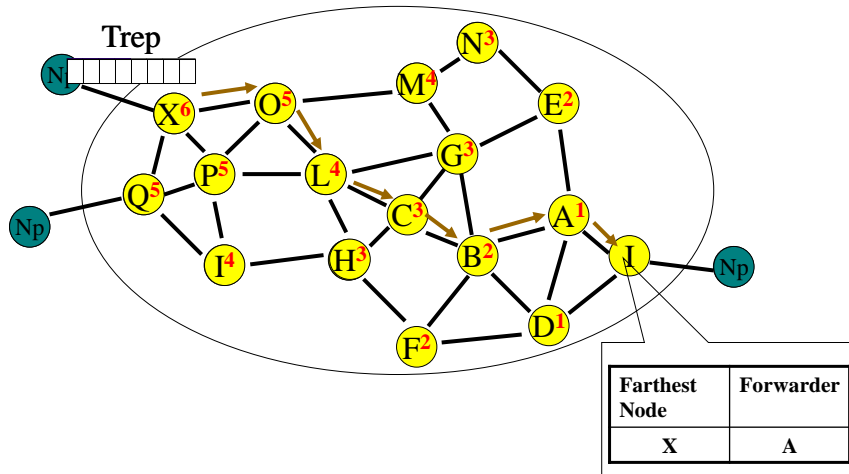
## Identifying the Farthest Nodes



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## Identifying the Farthest Nodes



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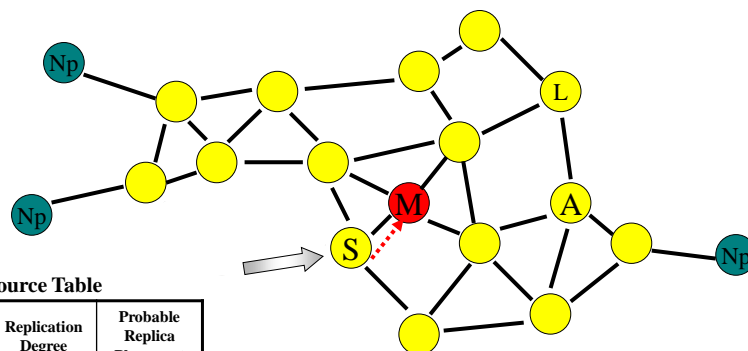
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## Degree of Replication: Approximated Consistency

*It relaxes* the constraint of *anytime perfect consistency* for the number of available replicas




Shared Resource Table

| Resource Name            | Replication Degree | Probable Replica Placement |
|--------------------------|--------------------|----------------------------|
| AlbertoTomba<br>Picture1 | 3                  | L, A, S                    |

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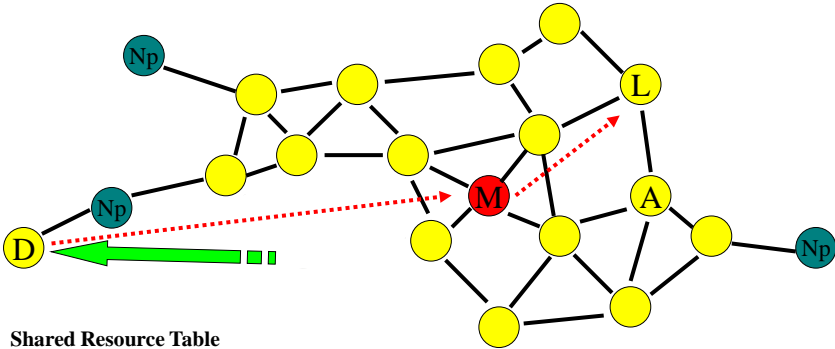
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## Degree of Replication: Approximated Consistency




**Shared Resource Table**

| Resource Name            | Replication Degree | Probable Replica Placement |
|--------------------------|--------------------|----------------------------|
| AlbertoTomba<br>Picture1 | 3                  | <del>X</del> L, A          |

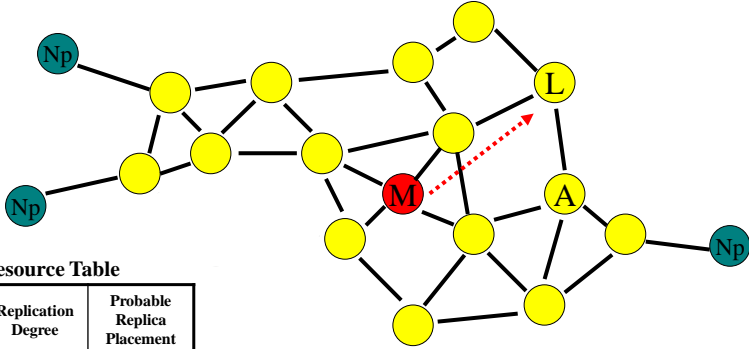
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## Degree of Replication: Approximated Consistency



**Shared Resource Table**

| Resource Name        | Replication Degree | Probable Replica Placement |
|----------------------|--------------------|----------------------------|
| AlbertoTomba<br>Pic1 | 3                  | <del>X</del> L, A          |

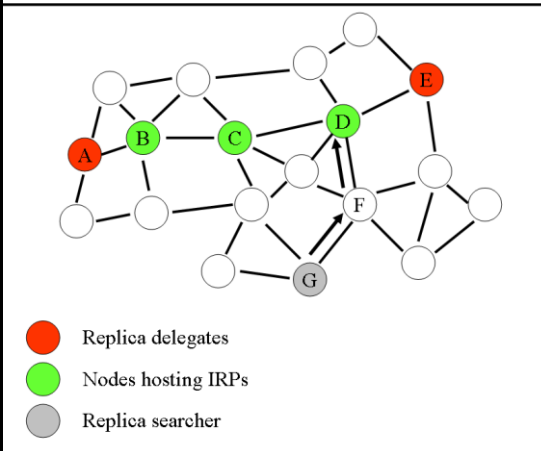
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## Strategies for Replica Dissemination

- Different possible strategies:
- Random** distribution
  - Spatially uniform** distribution
  - ...



REDMAN: distribution along “**straight lines**” (approxim.)

- No positioning equipment
- Straight lines: neighbors with the **lowest number of neighbors shared** with the previous nodes



## Strategies for Replica Retrieval

Different possible strategies for **replica retrieval**:

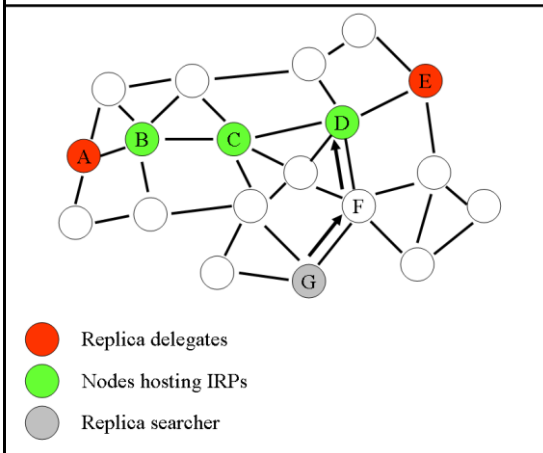
- **Query** flooding (QF)
- Flooding of **Information about Replica Placement** (IRP)
- **k-hop Distance IRP Dissemination (k-DID)**



REDMAN exploits **Straight IRP Dissemination (SID)**



## Strategies for Replica Retrieval



IRP are distributed along the **same approx. straight lines** used for replica dissemination

**Retrieval along straight lines** (*non parallel* to the lines used for dissemination)

**Duality between replica distribution and retrieval**